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# A LEVEL: MEI MATHEMATICS

## TOPICS FOR AUTOGRAPH

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Pre-release material: [LARGE DATA SET](#)

### PURE MATHEMATICS: ALGEBRA

- a3 Solve  $ax^2 + bx + c = 0$ ; discriminant  $b^2 - 4ac$
- a5 Simultaneous equations
- a7 Inequalities eg  $y - x > 1$ ;  $y > ax^2 + bx + c$

### PURE MATHEMATICS: FUNCTIONS

- f4  $f(x)$ ,  $g(x)$  then  $y = g(f(x))$
- f6 Graphs including modulus
- C3 Quadratics: completing the square
- C4 Graphing polynomials; repeated roots
- C5 Turning points
- C6  $y = a/x$  and  $y = a/x^2$ ; asymptotes

### PURE MATHEMATICS: GRAPHS

- C7  $y = af(x)$ ,  $y = f(x) + a$ ,  $y = f(x + a)$ ,  $y = f(ax)$
- C8 Transformations of a graph
- C9 Stationery points and point of inflexion

### PURE MATHEMATICS: COORDINATE GEOMETRY

- g1 Lines: //  $m_1 = m_2$ ;  $\perp$   $m_1 m_2 = -1$
- g2 Distance between 2 points; mid-point
- g4 St line:  $y - y_1 = m(x - x_1)$ ,  $ax + by + c = 0$
- g6 Intersection: 2 lines, line and curve, 2 curves
- g9 Intersection: line and circle
- g10 Circle:  $(x - a)^2 + (y - b)^2 = r^2$ ; angle properties
- g12 Parametric eqns: cartesian to parametric
- g14 Parametric eqns: circle
- g15 Gradient:  $dy/dx = (dy/dt)/(dx/dt)$
- g16 Kinematics and projectiles

### PURE MATHEMATICS: TRIGONOMETRY

- t1 Graphs of  $y = \sin\theta$ ,  $\cos\theta$ ,  $\tan\theta$  for any angle
  - t2 Symmetry, period, transformations
  - t5  $\tan\theta = \sin\theta/\cos\theta$
  - t6  $\sin^2\theta + \cos^2\theta = 1$
  - t7 Solving trig equations, eg  $\sin\theta = 0.5$  [ $0^\circ$ ,  $360^\circ$ ]
  - t9  $\arcsin x$ ,  $\arccos x$ ,  $\arctan x$ ;  $\sin^{-1}x$ ,  $\cos^{-1}x$ ,  $\tan^{-1}x$
  - t10 The radian
  - t11 Circle: arc length  $s = r\theta$ , sector  $A = \frac{1}{2}r^2\theta$
  - t12 Small angles:  $\sin\theta \approx \theta$ ,  $\cos\theta \approx 1 - \frac{1}{2}\theta^2$ ,  $\tan\theta \approx \theta$
  - t13  $\sec\theta$ ,  $\operatorname{cosec}\theta$ ,  $\cot\theta$
  - t14 Graphs of  $\sin\theta$ ,  $\cos\theta$ ,  $\tan\theta$ ,  $\operatorname{cosec}\theta$ ,  $\sec\theta$ ,  $\cot\theta$
  - t15  $\tan^2\theta + 1 = \sec^2\theta$ ,  $\cot^2\theta + 1 = \operatorname{cosec}^2\theta$
  - t16 Trig identities:  $\sin(\theta \pm \phi)$ ,  $\cos(\theta \pm \phi)$ ,  $\tan(\theta \pm \phi)$
  - t17 Double angles:  $\sin 2\theta$ ,  $\cos 2\theta$ ,  $\tan 2\theta$
  - t18  $a\cos\theta \pm b\sin\theta = r\sin(\theta \pm \alpha)$  and  $r\cos(\theta \pm \alpha)$
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### PURE: EXPONENTIALS AND LOGARITHMS

- E1  $y = a^x$ ;  $x = a^y \Leftrightarrow y = \log_a x$
- E7 Reduce exponential data to linear form
- E8  $y = e^x$
- E9 Gradient of  $y = e^{(kx)}$  is  $ke^{kx}$
- E10  $y = \ln x$  and its inverse  $y = e^x$
- E11 Exponential growth and decay

### PURE MATHEMATICS: CALCULUS

- c1 Gradient at a point: gradient of tangent
- c3  $dy/dx \approx \lim(\delta y/\delta x)$ ;  $\lim(((f(x+h)-f(x))/h)$
- c4 Sketch the gradient function
- c5 Differentiating  $y = kx^n$
- c6 The second derivative; max and min
- c8 The sign of  $dy/dx$
- c9 Equation of tangent and normal
- c10 Differentiate:  $e^{(kx)}$ ,  $a^{(kx)}$ ,  $\ln(x)$
- c11 Differentiate:  $\sin kx$ ,  $\cos kx$ ,  $\tan kx$
- c12 Differentiate: Product rule; Quotient rule
- c14 Differentiate:  $dy/dx = ((dy/du) \times (du/dx))$
- c15 Differentiate:  $dy/dx = 1/((dx/dy))$
- c16 Differentiate: implicit functions eg  $(x+y)^2 = 2x$
- c19 Integrate: fundamental theorem of calculus
- c20 Integrate:  $y = kx^n$
- c21 Integrate: constant; indefinite and definite
- c23 Integrate: area under a curve
- c24 Integrate:  $e^{kx}$ ,  $1/x$ ,  $\sin kx$
- c25 Integrate: limit of a sum
- c26 Integrate: area between two curves
- c32 1st order differential eqns: separating vars.
- c33 1st order differential eqns: links to kinematics

### PURE MATHEMATICS: NUMERICAL METHODS

- e3  $x = g(x)$ :  $x^3 - x - 4 = 0 \rightarrow x = (x+4)^{1/3}$
- e4 Newton-Raphson method; failures
- c34 Integration: trapezium rule; rectangles
- c35 Integration: upper and lower bound

### PURE MATHEMATICS: VECTORS

- v1 2D vectors: modulus, unit vector, parallel
  - v2 2D vectors: add, subtract, multiply by a scalar
  - v3 2D vectors: magnitude and direction
  - v4 2D vectors: position vectors
  - v5 2D vectors: distance between two points
  - v6 2D vectors: vectors representing forces
  - v7 3D vectors
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## STATISTICS: SAMPLING

p21 Population and sample; Sampling techniques

## STATISTICS: DATA

- D1 Discrete, continuous, ranked, grouped;  
bar chart, dot plot, stem-and-leaf  
box-and-whisker, frequency chart
- D2 Histogram: frequency density
- D3 Cumulative frequency diagram
- D4 Describe: symmetrical, skewed
- D6 Bivariate: scatter diagram; regression line  
Extrapolation: outliers; correlation
- D9 Time series
- D10 Central tendency: median, mode, mean
- D11 Measures of spread: range, quartiles, IQR
- D12 Variance and standard deviation
- D13 Outliers:  $\text{mean} \pm 2\text{SD}$ ;  $1.5 \times \text{IQR}$

## STATISTICS: PROBABILITY DISTRIBUTIONS

- R3 Binomial: calculate probabilities;  $\text{mean} = np$
- R7 Discrete uniform distribution
- R8 Normal Distribution: continuity correction  
Normal Distribution: binomial approximation
- R9 Normal Distribution: area  $\rightarrow$  probability
- R10 Normal Distribution:  $z = (x - \mu)/\sigma$
- R11 Normal:  $\text{mean} \pm \sigma = \text{points of inflexion}$

## STATISTICS: STATISTICAL HYPOTHESIS TESTING

- H1 Null/alternative, 1, 2-tailed test
- H6 Critical and acceptance regions
- H7 Samples,  $n$ , from  $X \rightarrow N(\mu, \sigma^2) \rightarrow N(\mu, \sigma^2/n)$
- H8 Test using Normal: Critical regions

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## MECHANICS: KINEMATICS IN 1 DIMENSION

- k4 Displacement, velocity, acceleration, time;  
significance of gradient and area
- k7 Const. Accel.:  $s = ut + \frac{1}{2}at^2$ ,  $v = u + at$ ,  $v^2 - u^2 = 2as$

## MECHANICS: KINEMATICS IN 2 DIMENSIONS

- k9 2D vectors: distance, velocity, acceleration
- k11 Equation of path from vectors

## MECHANICS: PROJECTILES

- y1 Motion under gravity, using vectors
- y2 Position, velocity, range, max height
- y3 Initial velocity; Angle of projection
- v5 Trajectory of a projectile
- v6 Range on a uniform slope

References to

[MEI A LEVEL MATHEMATICS](#)

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# MEI FURTHER MATHEMATICS

## TOPICS FOR AUTOGRAPH

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### CORE PURE: COMPLEX NUMBERS

- j1 Real, imaginary, conjugate, modulus  
argument, imaginary axis
- j2 Solving any quadratic; conjugate pairs;  
solving cubic/quartic equations
- j4 Add, subtract, multiply, divide; Zero
- j7 Modulus-argument form:  $z = r(\cos\theta + i\sin\theta)$
- j8  $z_1 z_2 = r_1 r_2 (\cos(\theta_1 + \theta_2) + i\sin(\theta_1 + \theta_2))$   
 $z_1 / z_2 = r_1 / r_2 (\cos(\theta_1 - \theta_2) + i\sin(\theta_1 - \theta_2))$
- j9 Sum, difference, product, quotient
- j11 Sets of complex numbers as loci  
Circles of the form  $|z - a| = r$   
Half lines of the form  $\arg(z - a) = \theta$   
Lines of the form  $|z - a| = |z - b|$
- j12 De Moivre's theorem:  $z = e^{i\theta} = \cos\theta + i\sin\theta$
- j17  $n$ th roots: sum are zero

### CORE PURE: MATRICES AND TRANSFORMATIONS

- m4 2-D: transformations using matrices  
reflect, rotate, enlarge, stretch, shear
- 3-D: transformations using matrices  
reflection in  $x=0$ ,  $y=0$ ,  $z=0$   
rotation  $90^\circ$  about  $x$ ,  $y$  or  $z$  axis
- m7 Determinant of  $2 \times 2$  and  $3 \times 3$ ; singular
- m8 Area scale factor
- m9 Determinant of  $3 \times 3$

### CORE PURE: VECTORS AND 3-D SPACE

- v1 Dot product; angle between 2 vectors  
 $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos\theta = a_1 b_1 + a_2 b_2 + a_3 b_3$
  - v2 Vector equation of a plane:  $(\mathbf{r} - \mathbf{a}) \cdot \mathbf{n} = 0$ ;  $\mathbf{d} = -\mathbf{a} \cdot \mathbf{n}$   
Cartesian form of plane:  $n_1 x + n_2 y + n_3 z + d = 0$
  - v3 Vector perpendicular to a plane
  - v4 3 distinct planes in 3-D
  - v5 3 linear simultaneous eqns; intersections
  - v6 Angle between two planes
  - v7 Vector product, perpendicular to two vectors
  - v8 Vector product,  $\mathbf{a} \times \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \sin\theta \mathbf{n}$
  - v9 Vector equation of a line in 2D and 3D
  - v10 Angle between two lines
  - v11 2 lines in 3D: intersection, shortest distance
  - v14 Intersection of a line and plane
  - v15 angle between a line and a plane
  - v16 Distance from a point to a line
  - v17 Distance from a point to a plane
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**CORE PURE: SERIES**

s3 Maclaurin:  $e^x$ ,  $\ln(1+x)$ ,  $\sin x$ ,  $\cos x$ ,  $(1+x)^n$

**CORE PURE: CALCULUS**

- c1 Definite integrals
- c2 Volume of revolution about x- or y-axis
- c3 Mean value of a fn:  $1/(b-a)\int f(x)dx$ , limits a-b
- c4 Differentiate inverse trig functions

**CORE PURE: POLAR COORDINATES**

- P1 Polar coordinates
- P2  $r = a(1+\cos\theta)$ ,  $r = a\cos 2\theta$  [ $r < 0$  broken line]
- P3 Area enclosed by a polar curve  $A = \frac{1}{2}\int r^2 d\theta$

**CORE PURE: HYPERBOLIC FUNCTIONS**

- a3  $\sinh x$ ,  $\cosh x$ ,  $\tanh x$ ;  $\cosh^2 x - \sinh^2 x = 1$
- a5 differentiate and integrate hyperbolics
- a6 inverse hyperbolic functions; log forms

**CORE PURE: DIFFERENTIAL EQUATIONS**

- c7 1st order: general soln and particular integral
- c8 Integrating factor:  $y' + P(x)y = Q(x)$
- c11 2nd order:  $y'' + ay' + by = 0$  auxiliary equation
- c12 Interpretation of the discriminant
- c13  $y'' + ay' + by = f(x)$
- v11 SHM  $x'' + cx = 0$ ,  $x'' = -\omega^2(x+k) \rightarrow x = A\cos(\omega t - \phi)$
- v12 Amplitude, T period =  $(2\pi)/\omega$ ,  $v^2 = \omega^2(A^2 - x^2)$
- c16 Damped SHM
- c17 Critical damping, roots of auxiliary equation
- c18 Coupled 1st order linear, eg predator-prey

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**STATISTICS: DISCRETE RANDOM VARIABLES**

- R7 Discrete uniform distribution
- R10 Binomial distribution:  $\mu = np$ ,  $\sigma^2 = npq$
- R11 Poisson distribution:  $\mu = \lambda$ ,  $\sigma^2 = \lambda$
- R16 Geometric distribution:  $\mu = 1/p$ ,  $\sigma^2 = (1-p)/p^2$

**STATISTICS: BIVARIATE DATA**

- b1 Scatter diagram; outliers; PMCC
- b8 Spearman's Rank
- b11 Equation of least squares regression
- b12 Residuals; Two regression lines

**STATISTICS: CONTINUOUS RANDOM VARIABLES**

- R19 Uniform and Normal distributions
- R29 Normal distribution
- R30 Central Limit Theorem

**STATISTICS MAJOR: INFERENCE**

- I3 Distribution of the sample mean
  - I4 Central Limit Theorem
  - I7 Confidence Intervals
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**NUMERICAL METHODS: SOLVING EQUATIONS**

- e1 Bisection method, staircase and cobweb diagrams
- e3 Fixed point iteration; Newton-Raphson

**NUMERICAL METHODS: INTEGRATION**

- c3 Midpoint and trapezium rules; Simpson's rule

**EXTRA PURE: MULTIVARIABLE CALCULUS**

- c1  $z = f(x,y)$  is a surface, eg  $z = xy^2 - 4x^2y + 20$

**FURTHER PURE WITH TECHNOLOGY: INVESTIGATION OF CURVES**

- C1 Family of curves in cartesian, polar and parametric forms
- C8 Arc length
- C9 Envelope of a family of curves

**FURTHER PURE WITH TECHNOLOGY: EXPLORING DIFFERENTIAL EQUATIONS**

- c1 1st order Differential equations
- c2 Tangent field
- c7 Euler method or a modified Euler method
- c9 Runge-Kutta method

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References to

[MEI A LEVEL FURTHER MATHEMATICS](#)

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